

Lecture 12 - Oct 20

Graphs

Adapting DFS for Graph Questions

BFS: Marking Vertices and Edges

BFS: First Example on a Tree

Announcements/Reminders

- Today's class: notes template posted
- **Assignment 1** due on Wednesday, October 22
- **Test 1** next Monday, October 27:
 - + **Guide** released *not yet (Tuesday)*
 - + **Review Session** (slides, notes): Wednesday
 - + **Review Session** (A1, more Q&A): Friday
- **Tutorial Exercises** so far:
 - + **Tutorial Week 1** (2D arrays)
 - + **Tutorial Week 2** (2D arrays, Proving Big-O)
 - + **Tutorial Week 3** (avg case analysis on doubling strategy)
 - + **Tutorial Week 4** (Trinode restructuring after deletions)

Test 1 (WSC, 4:30 PM to 5:20 PM)

• Coverage

Monday, Oct 27

+ Lecture materials (slides, notes, example code)

up to and including Monday, October 20

+ Tutorials 1 to 4

+ Assignment 1

eClass: 100 marks
programming part: X marks

• Format

+ Programming Part (Eclipse):

* Import a Java starter project (like A1)

* Implement Java classes/methods to pass test cases

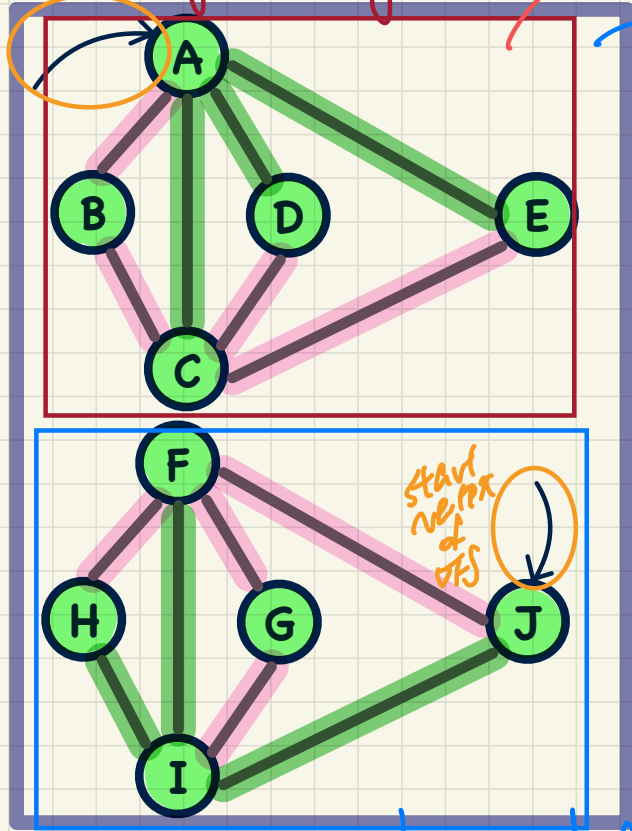
+ Written Part (eClass):

* Primarily MCQs

→ Two choice

* Written questions (e.g., short answers, justifications, proofs)

Start vertex of DFS subgraph traversed by 1st DFS



a DFS starting at vertex A is guaranteed to visit all vertices in the C.C. that A belongs to

→ not connected

→ 1 Connected Components

↳ multiple passes of traversal

↳ - DFS

- BFS

RT of DFS

$$O(|V| + |E|)$$

→ assumption getting a vertex's incident

edges is $O(1)$

not the case for edge list strategy

↓ Connected component traversed by 2nd DFS.

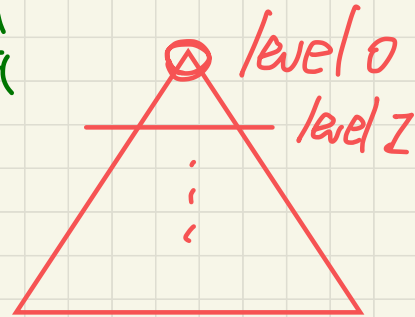
Graph Traversal

Assume G is connected

a DFS gives a ^{DFS tree} spanning tree of G

a BFS gives a spanning tree of G

BFS tree,
level tree



If input graph G is not assumed to be connected.
boolean done = false;

while (! done.) {

dfs (some unvisited vertex)

if (# visited nodes so far = $|V|$) {
done = true
}

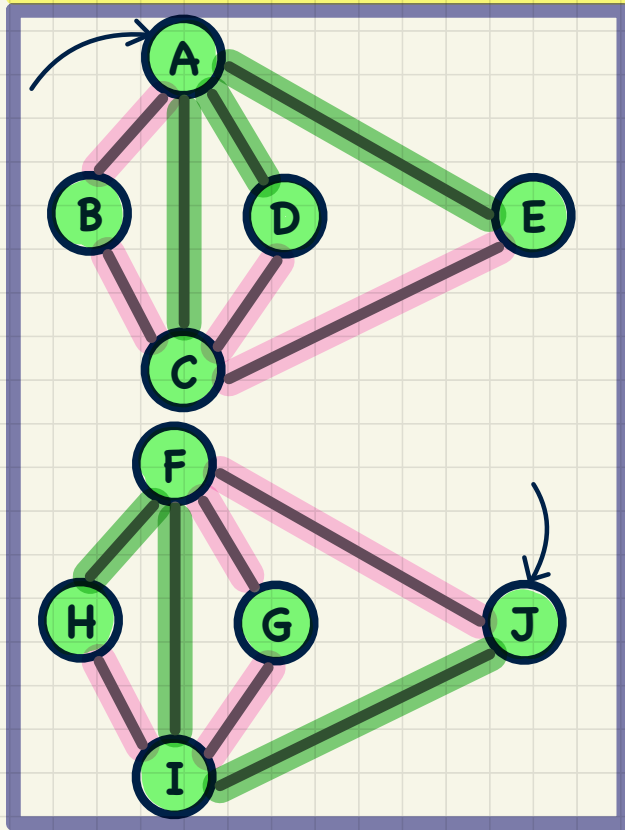
}

iterations
" "
connected components.

* a single DFS can return a single C.C.

Graph Traversals: Adapting DFS

Efficient Traversal of Graph G:



4. if v is never encountered, then path does not exist!

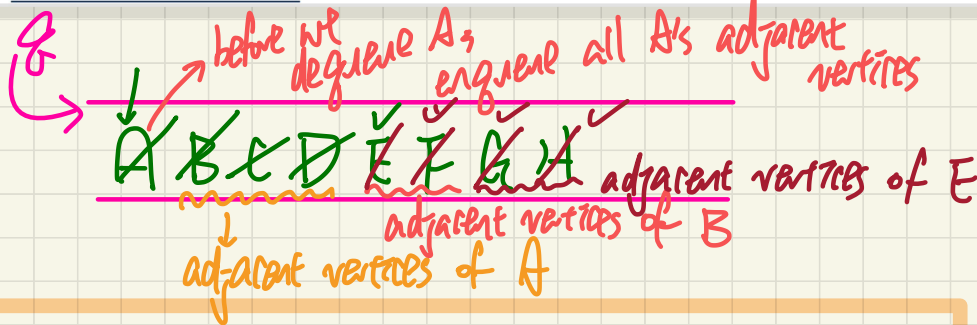
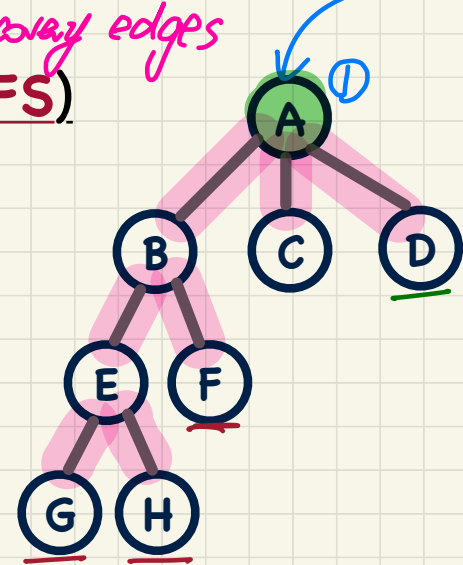
Graph Questions:

- Find a **path** between $\{u, v\} \subseteq V$ *the best so far.*
 1. start a DFS from u .
 2. Maintain a list to store the visited vertices.
 3. if v is visited, return.
- Is u **reachable** from v *similar to calculating a path*
- * Find **all connected components** of G .
- Compute a **spanning tree** of a **connected** G .
 - $\hookrightarrow$ # discovery edges = # edges in G - 1
- Is G **connected**?
 - $\hookrightarrow$ # visited nodes $\stackrel{?}{=} |V|$
- If G is cyclic, return a **cycle**.
 - $\hookrightarrow$ return the path that leads to a back edge.

Graph Traversal: Breadth-First Search (BFS)

A **breadth-first search (BFS)** of graph $G = (V, E)$, starting from some vertex $v \in V$:

- Visits every vertex **adjacent** to v before visiting any other (**more distant**) vertices
 - BFS** attempts to stay as **close** as possible, whereas **DFS** attempts to move as **far** as possible
 - BFS** proceeds in rounds and divides the vertices into **levels**
- No backtracking** in **BFS**: it is completed **as soon as** the **most distant level** of vertices from the start vertex v are visited.



Q. What data structure should be used to keep track of the visited nodes?

FIFO queue

Breadth-First Search (BFS): Marking Vertices & Edges

Before the **BFS** starts:

- All vertices are **unvisited**.
- All edges are **unexplored/unmarked**.

Over the course of a **BFS**, we **mark** vertices and edges:

- A vertex is marked **visited** when it is **first** encountered.
 - Then, we iterate through each of v 's **incident edges**, say e :
 - If edge e is already **marked**, then skip it.
 - Otherwise, for an **undirected** graph, an edge is marked as:
 - A **discovery** edge if it leads to an **unvisited** vertex
 - A **cross** edge if it leads to a **visited** vertex
- (i.e., from a **different branch** at the **same level**).

